# NFGen: Automatic Non-linear Function Evaluation Code Generator for General-purpose MPC Platforms

Xiaoyu Fan, Kun Chen, Guosai Wang, Mingchun Zhuang, Yi Li and Wei Xu ACM CCS 2022







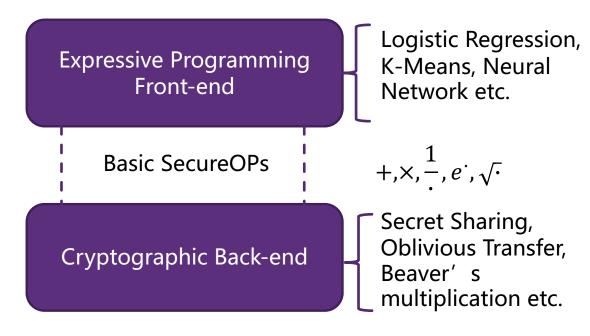
## General-purpose Multi-party Computation

- Secure multi-party computation (MPC) offers a promising way to achieve privacy-preserving computation.
- Currently, several general-purpose
   MPC platforms are proposed.
  - High efficiency.
  - Expressive programming front-end.
  - Making the development of complex applications possible.



## General-purpose Multi-party Computation

- Secure multi-party computation (MPC) offers a promising way to achieve privacy-preserving computation.
- Currently, several general-purpose
   MPC platforms are proposed.
  - High efficiency.
  - Expressive programming front-end.
  - Making the development of complex applications possible.



Basic Structure of General-purpose MPC platforms

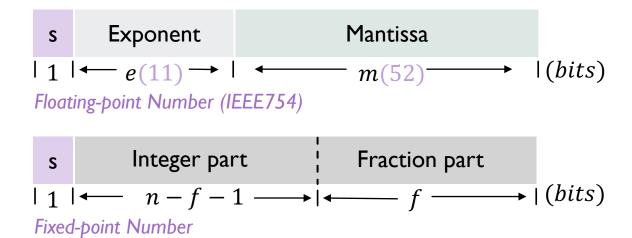
E.g., Platforms surveyed in [HHNZ19], MP-SPDZ[Kel20], ABY3[MR18]...



# Fixed-point Number and Non-linear Function Evaluation

Fixed-point(FXP) vs. Floating-point(FLP)

|          | FXP                       | FLP(IEEE74)                   |  |  |
|----------|---------------------------|-------------------------------|--|--|
| Range    | $[-2^{n-f-1}, 2^{n-f-1}]$ | $[-2^{2^{e-1}}, 2^{2^{e-1}}]$ |  |  |
| Smallest | $2^{-f}$                  | $2^{1-2^{e-1}}$               |  |  |





# Fixed-point Number and Non-linear Function Evaluation

Fixed-point(FXP) vs. Floating-point(FLP)

|          | FXP                       | FLP(IEEE74)                   |  |
|----------|---------------------------|-------------------------------|--|
| Range    | $[-2^{n-f-1}, 2^{n-f-1}]$ | $[-2^{2^{e-1}}, 2^{2^{e-1}}]$ |  |
| Smallest | $2^{-f}$                  | $2^{1-2^{e-1}}$               |  |

- s Integer part Fraction part  $| 1 | \longleftarrow n f 1 \longrightarrow | \longleftarrow f \longrightarrow | \text{ (bits)}$ Fixed-point Number
- Current non-linear function evaluation
  - Hand-crafted design a series of basic Ops like  $\frac{1}{\cdot}$ ,  $e^{\cdot}$ ,  $\sqrt{\cdot}$  etc.
  - Express complex functions as sequential combinations of basic Ops.

$$tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

I. compute  $e^x$  and  $e^{-x}$ 

2. compute the division.

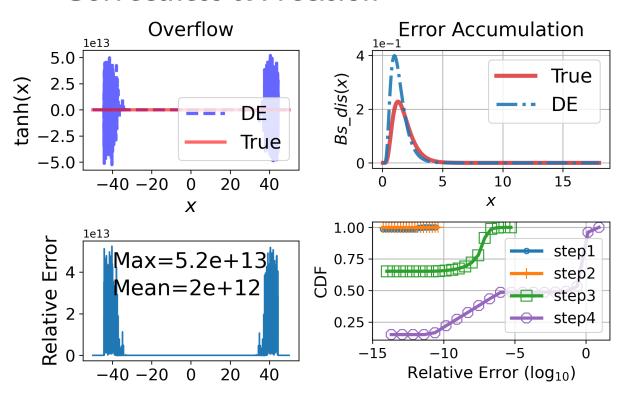


# Pitfalls of Current Non-linear Function Evaluation



#### Pitfalls of Current Non-linear Function Evaluation

#### Correctness & Precision

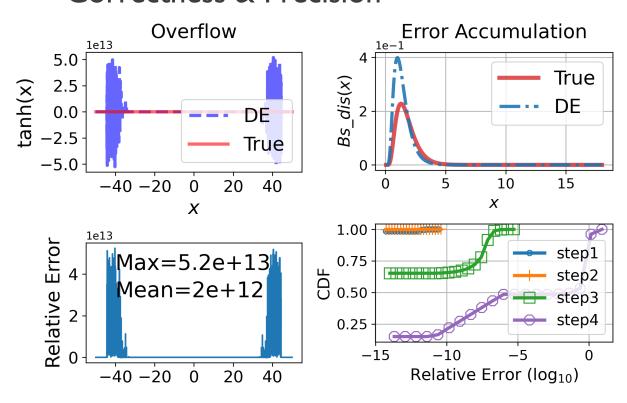


Error Cases in Current MPC Platforms (DE: Direct Evaluation)



#### Pitfalls of Current Non-linear Function Evaluation

#### Correctness & Precision



Error Cases in Current MPC Platforms (DE: Direct Evaluation)

#### Performance

• Non-linear building blocks are far expensive than  $+,\times$ .

#### Generality

• Not support hard-to-compute functions like  $\gamma(x, z)$ ,  $\Phi(x)$ .

#### Portability

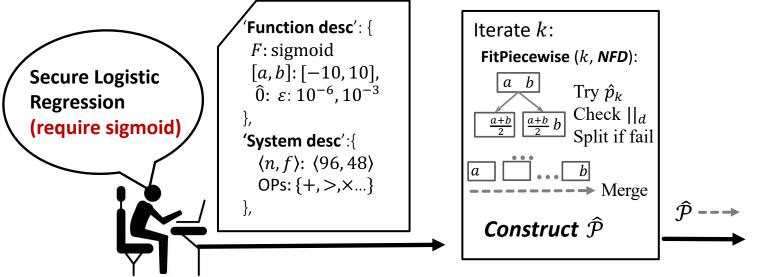
 Non-linear function design for one platform is hard to transplant to others.



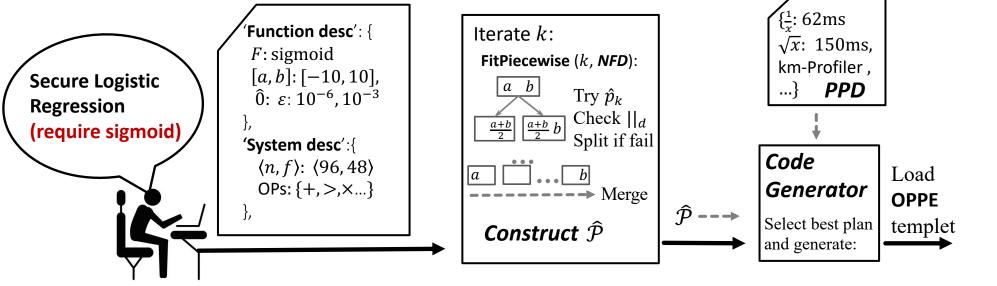
```
Secure Logistic Regression (require sigmoid)

(require (a, b): [-10, 10], (a, b): [-10, 10], (a, b): (a,
```

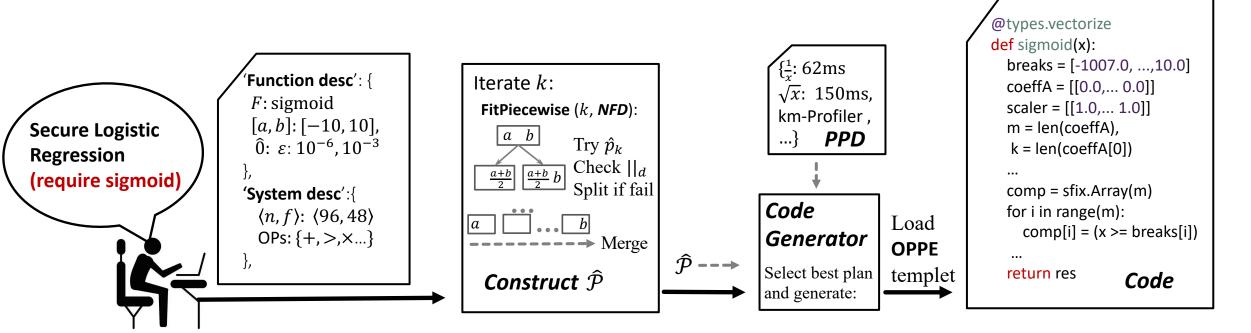












End-to-End Workflow of NFGen

Open source: https://github.com/Fannxy/NFGen



- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - > Best-effort try-split until succeed.

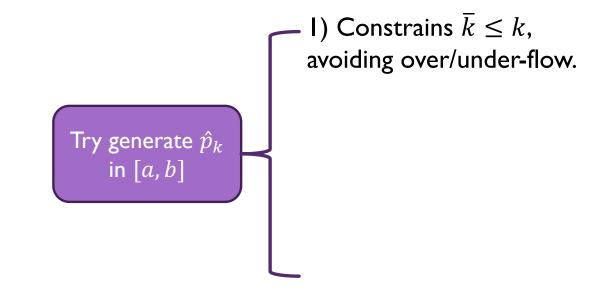


- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ -FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - > Best-effort try-split until succeed.

Try generate  $\hat{p}_k$  in [a, b]

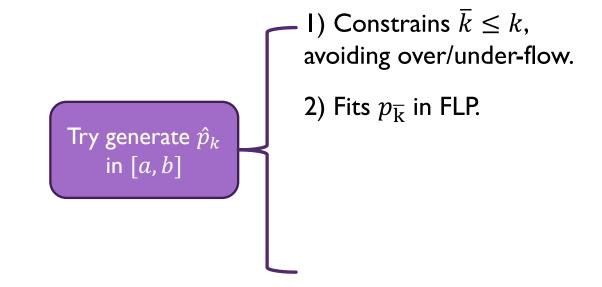


- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - > Best-effort try-split until succeed.





- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - > Best-effort try-split until succeed.





- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - Best-effort try-split until succeed.

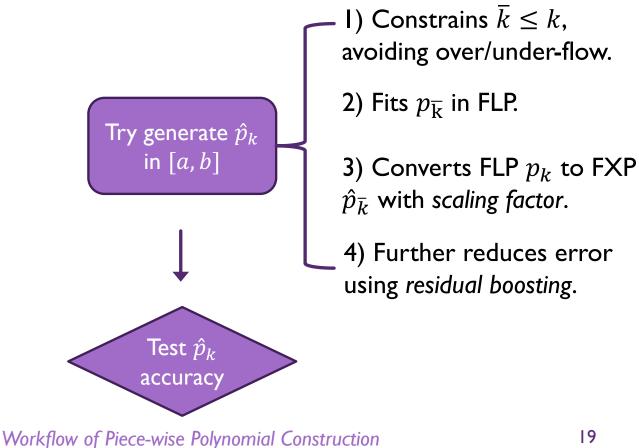
I) Constrains  $\bar{k} \leq k$ , avoiding over/under-flow. 2) Fits  $p_{\bar{k}}$  in FLP.

- 3) Converts FLP  $p_k$  to FXP  $\hat{p}_{\bar{k}}$  with scaling factor.
- 4) Further reduces error using residual boosting.



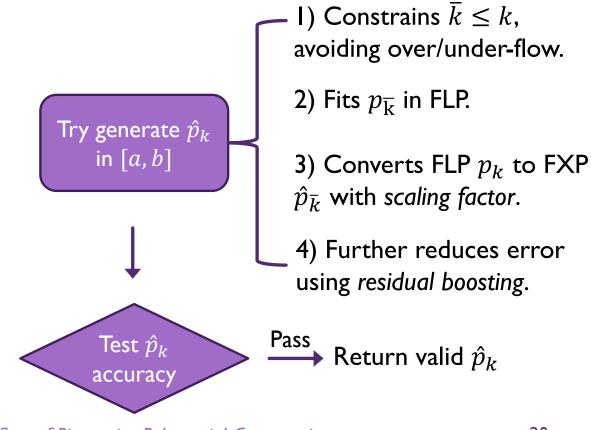
in [*a*, *b*]

- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ -FXP.
  - ➤ NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x)satisfying the accuracy requirement.
  - Best-effort try-split until succeed.





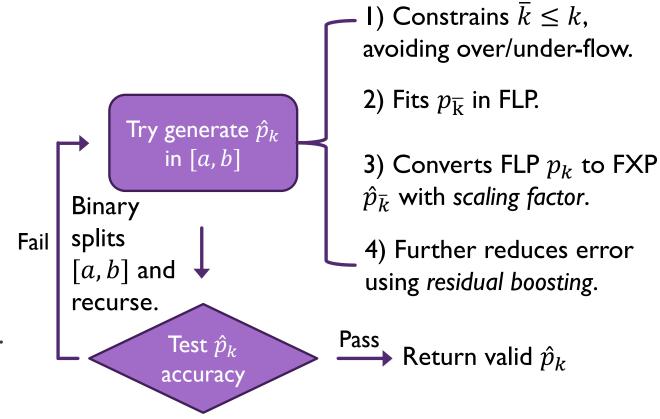
- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - Best-effort try-split until succeed.







- Valid piece-wise polynomial  $\hat{p}_k^m$ 
  - Each term in piece-wise polynomial  $\hat{p}_k^m$  can be represented by  $\langle n, f \rangle$ -FXP.
  - NP-Complete Integer programming problem.
  - $\hat{p}_k^m(x)$  can approximate F(x) satisfying the accuracy requirement.
  - Best-effort try-split until succeed.



Workflow of Piece-wise Polynomial Construction



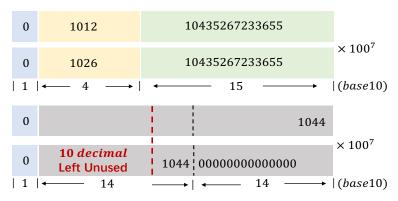
Severe problem: tiny coefficients in FXP harm the final accuracy.



- Severe problem: tiny coefficients in FXP harm the final accuracy.
- Scaling factor
  - Making use of more significant bits.



- Severe problem: tiny coefficients in FXP harm the final accuracy.
- Scaling factor
  - Making use of more significant bits.
    - E.g., computing  $7^{\text{th}}$  term  $(1.044 \times 10^{-11}) \times 100^7$



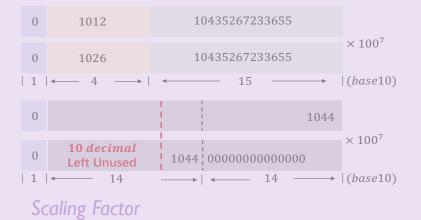
**Scaling Factor** 

Left shift the coefficients as much as possible while avoid overflow.



Severe problem: tiny coefficients in FXP harm the final accuracy.

- Scaling factor
  - Making use of more significant bits.
    - E.g., computing  $7^{\text{th}}$  term  $(1.044 \times 10^{-11}) \times 100^7$



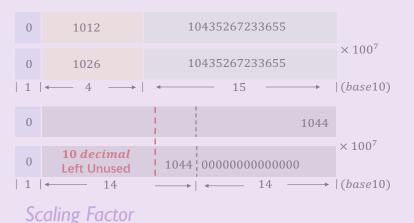
Left shift the coefficients as much as possible while avoid overflow.

- Residual Boosting
  - Lower-order polynomial tend to have larger coefficients.



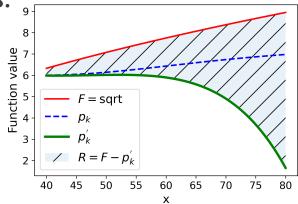
Severe problem: tiny coefficients in FXP harm the final accuracy.

- Scaling factor
  - Making use of more significant bits.
    - E.g., computing  $7^{\text{th}}$  term  $(1.044 \times 10^{-11}) \times 100^7$



Left shift the coefficients as much as possible while avoid overflow.

- Residual Boosting
  - Lower-order polynomial tend to have larger coefficients.
  - Use a series of lower-order polynomials to fill the residuals.



**Residual Function Demonstration** 



# Automatic Performance Profiler & Code Generation

- Piece-wise polynomial evaluation.
  - Secure: Obliviously organize secure +,× and >.
  - Performance: O(m) secure > and  $O(km + k \log k)$  secure ×.
  - Which  $\hat{p}_k^m$  has better performance depends on the characters of specific MPC deployment.



# Automatic Performance Profiler & Code Generation

- Piece-wise polynomial evaluation.
  - Secure: Obliviously organize secure +,× and >.
  - Performance: O(m) secure > and  $O(km + k \log k)$  secure ×.
  - Which  $\hat{p}_k^m$  has better performance depends on the characters of specific MPC deployment.

| MPC deploy ( $\mathcal{S}$ ) | ×(ms) | X:>  | Preference                 |  |
|------------------------------|-------|------|----------------------------|--|
| Rep2k(SPDZ)                  | 2     | 1:4  | More prefer less m         |  |
| RepF(SPDZ)                   | 32    | 1:1  |                            |  |
| Shamir(SPDZ)                 | 81    | 1:1  | Managara Land              |  |
| Ps-Rep2k(SPDZ)               | 851   | 1:1  | More prefer less $k$ .     |  |
| Ps-RepF(SPDZ)                | 84    | 1:1  |                            |  |
| Rep2k(PrivPy)                | I     | 1:11 | Severely prefer less $m$ . |  |

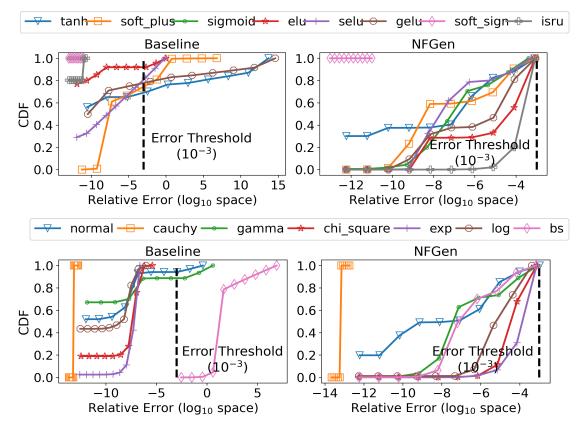
Performance Characteristic of Different MPC Deployments

- Train a deployment-specific profiler model  $f_S$ :  $(k, m) \rightarrow \text{time(ms)}$  and select the most efficient one.
- Generate code into pre-defined code templet.



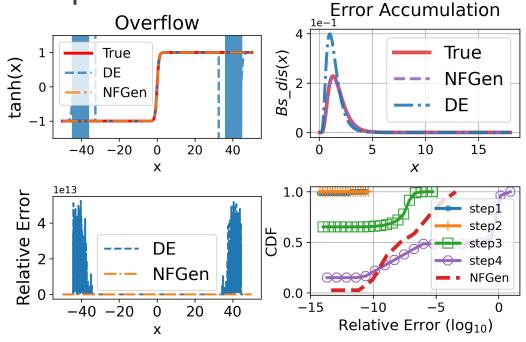
#### **Evaluation: Improved Accuracy**

Overview of 15 common-used functions



- Baseline: direct evaluation of MP-SPDZ library functions.
- NFGen: generated evaluation code.





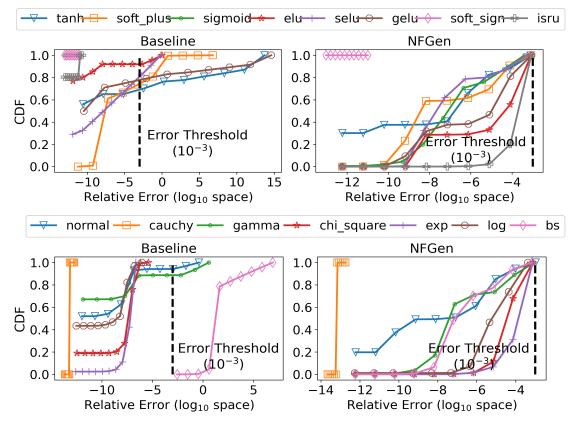
Improved Accuracy Cases

29

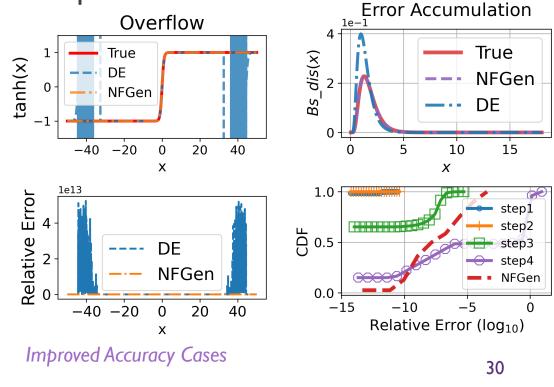


**Evaluation: Improved Accuracy** 

Overview of 15 common-used functions



#### Improved cases



library functions.

Baseline: direct evaluation of MP-SPDZ

NFGen: generated evaluation code.



#### **Evaluation: Improved Efficiency**

| MPC Sys            | Efficiency ratio(%), speedup(×) |       |       | Comm ratio(%), save(%) |      |     |
|--------------------|---------------------------------|-------|-------|------------------------|------|-----|
|                    | Benefit                         | Mean  | Max   | Benefit                | Mean | Max |
| Rep2k(SPDZ)        | 100%                            | 16.7× | 86.1× | 93%                    | 58%  | 93% |
| RepF(SPDZ)         | 100%                            | 5.3×  | 16.0× | 87%                    | 41%  | 87% |
| Shamir(SPDZ)       | 100%                            | 4.0×  | 10.9× | 87%                    | 30%  | 83% |
| Ps-<br>Rep2k(SPDZ) | 67%                             | 1.8×  | 6.1×  | 67%                    | 8%   | 84% |
| Ps-RepF(SPDZ)      | 87%                             | 2.3×  | 7.6×  | 73%                    | 27%  | 87% |
| Rep2k(PrivPy)      | 100%                            | 8.6×  | 29.1× | 93%                    | 57%  | 90% |

- NFGen achieves significant improvements.
  - 93% achieves benefit in all
     15 \* 6 cases.
  - Average speedup 6.5×
     and maximum 86.1×.
  - Average communication save 39.3% and maximum 93%.

Improved Performance Overview

15 functions for each sys and all achieve the above accuracy requirements.



#### **Evaluation: Improved Efficiency**

| MPC Sys            | Efficiency ratio(%), speedup(×) |       |       | Comm ratio(%), save(%) |      |     |
|--------------------|---------------------------------|-------|-------|------------------------|------|-----|
|                    | Benefit                         | Mean  | Max   | Benefit                | Mean | Max |
| Rep2k(SPDZ)        | 100%                            | 16.7× | 86.1× | 93%                    | 58%  | 93% |
| RepF(SPDZ)         | 100%                            | 5.3×  | 16.0× | 87%                    | 41%  | 87% |
| Shamir(SPDZ)       | 100%                            | 4.0×  | 10.9× | 87%                    | 30%  | 83% |
| Ps-<br>Rep2k(SPDZ) | 67%                             | 1.8×  | 6.1×  | 67%                    | 8%   | 84% |
| Ps-RepF(SPDZ)      | 87%                             | 2.3×  | 7.6×  | 73%                    | 27%  | 87% |
| Rep2k(PrivPy)      | 100%                            | 8.6×  | 29.1× | 93%                    | 57%  | 90% |

- NFGen achieves significant improvements.
  - 93% achieves benefit in all
     15 \* 6 cases.
  - Average speedup 6.5×
     and maximum 86.1×.
  - Average communication save 39.3% and maximum 93%.

Improved Performance Overview

15 functions for each sys and all achieve the above accuracy requirements.



# Evaluation: Other Benefits

#### Support hard-to-compute functions

| Target function                                                     | (k, m) | Fit time |
|---------------------------------------------------------------------|--------|----------|
| $\gamma(x,z) = \int_0^x t^{z-1} e^t dt$                             | (6, 4) | l.ls     |
| $\Gamma(x,z) = \int_{x}^{\infty} t^{z-1}e^{t} dt$                   | (6, 6) | l.ls     |
| $\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$ | (4, 6) | 0.8s     |
| $\Phi(x) = \frac{2}{\sqrt{2\pi}} \int_0^x e^{\frac{t^2}{2}} dt$     | (8, 6) | 1.2s     |

Hard-to-compute Functions



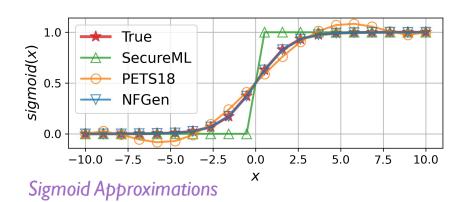
#### **Evaluation: Other Benefits**

#### Support hard-to-compute functions

| Target function                                                     | (k, m) | Fit time |
|---------------------------------------------------------------------|--------|----------|
| $\gamma(x,z) = \int_0^x t^{z-1} e^t dt$                             | (6, 4) | l.ls     |
| $\Gamma(x,z) = \int_{x}^{\infty} t^{z-1}e^{t} dt$                   | (6, 6) | l.ls     |
| $\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$ | (4, 6) | 0.8s     |
| $\Phi(x) = \frac{2}{\sqrt{2\pi}} \int_0^x e^{\frac{t^2}{2}} dt$     | (8, 6) | 1.2s     |

#### Accelerate current applications

• Approximate sigmoid(x) and accelerate LR.



Hard-to-compute Functions



#### Conclusion

- NFGen is our attempt to offer a new way evaluating non-linear functions in MPC,
  - Improved performance from many perspectives (correctness, precision and efficiency).
  - Easy to use: NFGen automatically generate the evaluation code with a simple input config.
  - Support numerous hard-to-compute functions and different bit lengths, making MPC systems more general than before.
- As MPC offers a brand-new architecture, maybe we should explore new algorithm design logic instead of just follow the plaintext development.



# Q&A

Thanks for your listening!

